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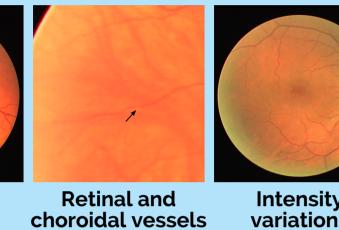
# INTRODUCTION

### motivation

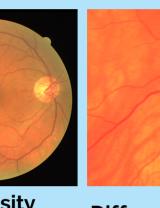
Retinal image analysis is greatly aided by blood vessel segmentation as the vessel structure may be considered both a key source of signal, e.g. in the diagnosis of diabetic retinopahy, or a nuisance, e.g. in the analysis of pigment epithelium or choroid related abnormalities.

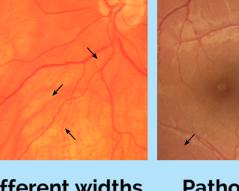
## challenges

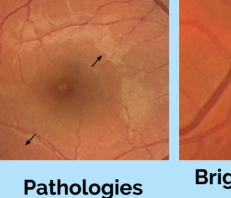


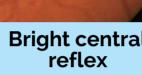












## our contribution

We present a novel method for blood vessel segmentation in fundus images based on a discriminatively trained,

fully connected conditional random field (CRF) [1].

# energy definition

The **segmentation task** is posed as an **energy** minimization problem in a fully connected CRF:

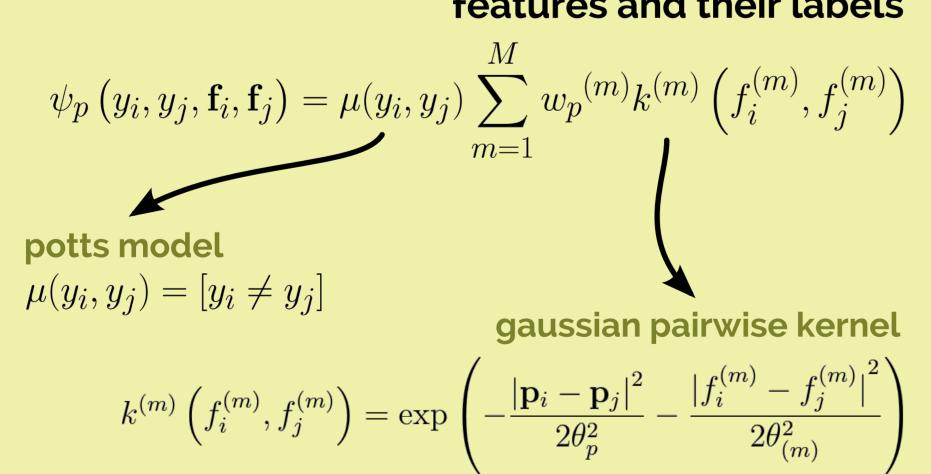
$$E(\mathbf{y}) = \sum_{i} \psi_{u}(y_{i}, \mathbf{x}_{i}) + \sum_{i < j} \psi_{p}(y_{i}, y_{j}, \mathbf{f}_{i}, \mathbf{f}_{j})$$

unary potentials Log-likelihood over

the label assignment:  $\psi_u(y_i, \mathbf{x}_i) = -\langle \mathbf{w}_{u_{y_i}}, \mathbf{x}_i \rangle - \beta_{y_i}$ 

#### pairwise potentials

Similar distribution but considering only the interactions between pixels features and their labels



## estimation of scale values

Scale values of the pairwise kernels are estimated following [2], by taking the median of the distance over random sampled pairs of pixels.

# LEARNING FULLY CONNECTED CRF'S PARAMETERS USING SOSVM

structured output sym We optimize this expression using [3]. feature map

$$\min_{\mathbf{w},\xi \ge 0} \frac{1}{2} ||\mathbf{w}||^2 + C\xi$$
s.t.  $\forall (\bar{y}^{(1)}, ..., \bar{y}^{(n)}) : \sum_{i=1}^{n} \langle \mathbf{w}, \varphi(s^{(i)}, y^{(i)}) - \varphi(s^{(i)}, \bar{y}^{(i)}) \rangle \ge \sum_{i=1}^{n} \Delta(y^{(i)}, \bar{y}^{(i)}) - \xi$ 

training set

Weights are learned from the training set:  $S = \{\left(s^{(1)}, y^{(1)}\right), ..., \left(s^{(n)}, y^{(n)}\right)\}$ unary feature vector, bias constant and pairwise feature vector  $s^{(i)}=\{x^{(i)},B,f^{(i)}\} \qquad y^{(i)}\in\mathcal{L}=\{-1,+1\} \quad \text{manual annotation}$ 

loss function Hamming loss  $\varphi(s, y) = \left(\sum_{k} \varphi_{u}(\mathbf{x}_{k}, y_{k}), \sum_{k} \varphi_{\beta}(B, y_{k}), \sum_{k} \sum_{j < k} \varphi_{p}\left(y_{k}, y_{j}, \mathbf{f}_{k}, \mathbf{f}_{j}\right)\right)$  $\Delta(y,\bar{y}) = \sum [y_i \neq \bar{y}_i]$  $\varphi_{u}(\mathbf{x}_{k}, y_{k}) = \mathbf{x}_{k} \otimes \varphi_{y}(y_{k}) \qquad \varphi_{\beta}(B, y_{i}) = B\varphi_{y}(y_{i}) \qquad \forall m : \left[\varphi_{p}\left(y_{k}, y_{j}, \mathbf{f}_{k}, \mathbf{f}_{j}\right)\right]_{m} = \mu(y_{i}, y_{j})k^{(m)}(f_{i}^{(m)}, f_{j}^{(m)})$ pairwise term

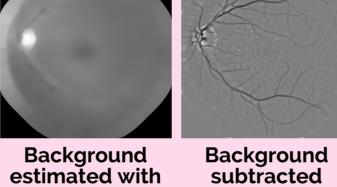
weight vector  $\mathbf{w}=(\mathbf{w}_u,\mathbf{w}_\beta,\mathbf{w}_p)$  weights for unary, bias and pairwise terms, respectively

# **FEATURES**

# preprocessing

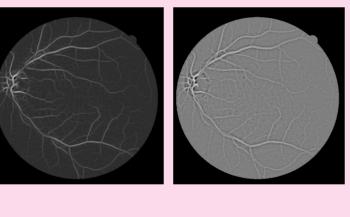
**Images** are **preprocessed** to **avoid** false detections in the border of the FOV and to reduce the effect of biased illumination.



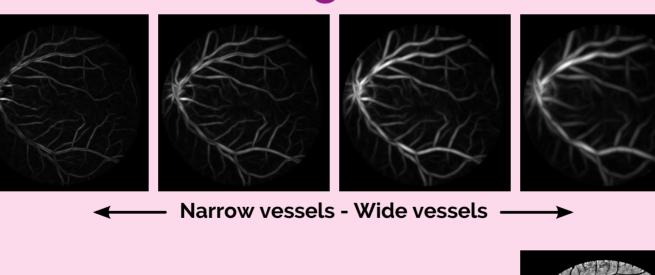


# unary features

line detectors [4]

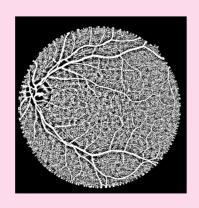


2d multiscale gabor wavelets [5]





### pairwise feature



vessel enhancement inspired on [7]

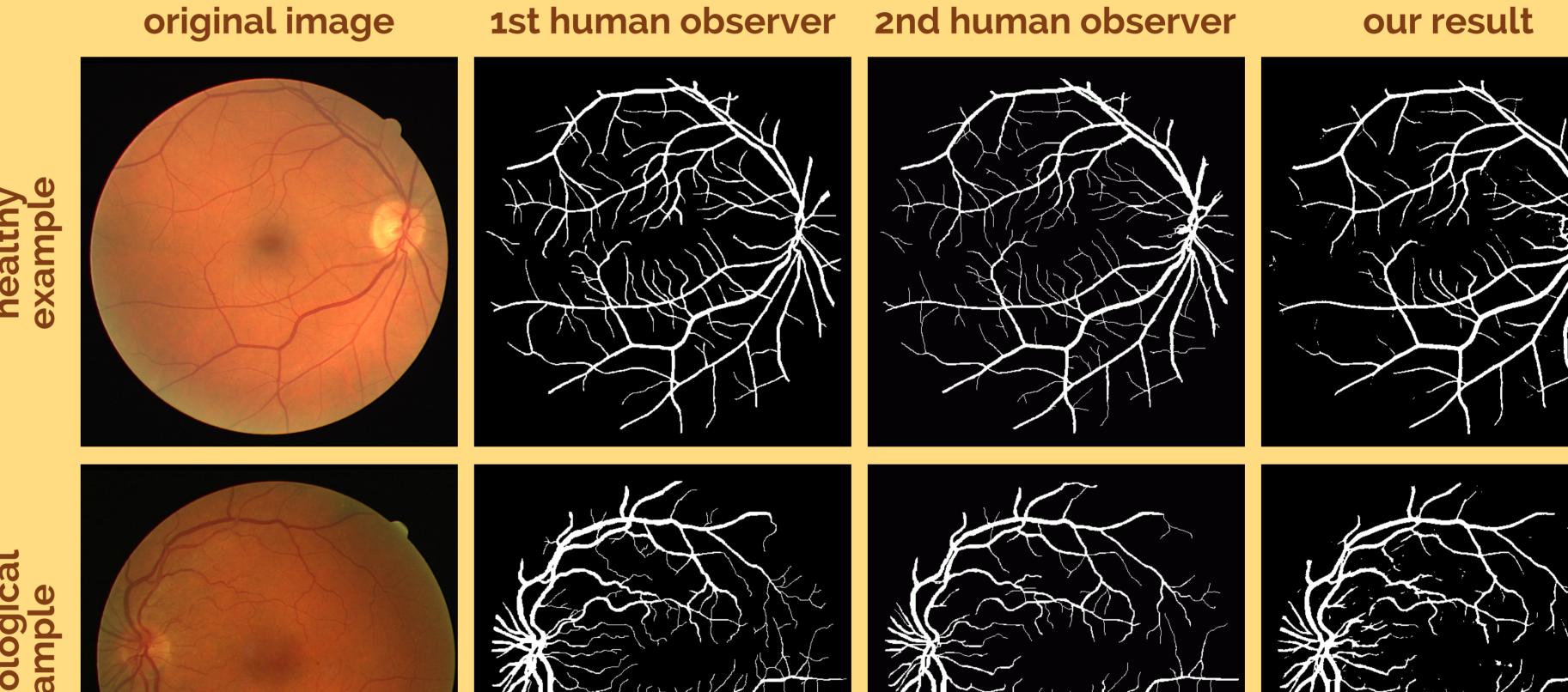
#### feature selection

Best configuration of features is found by minimizing the distance to a second human observer performance, using a validation set.

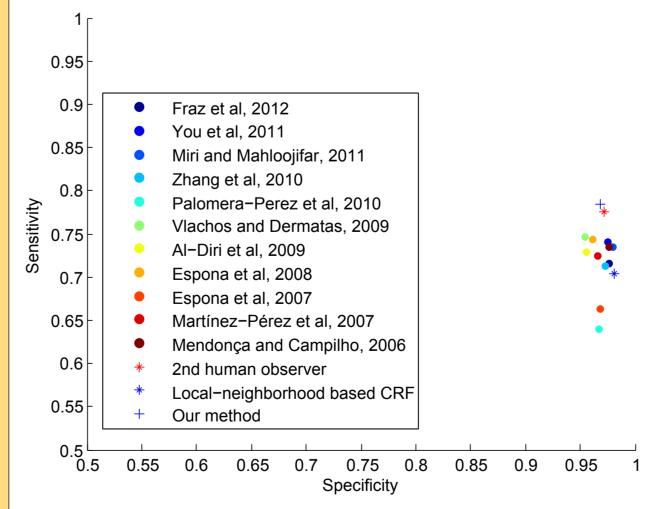
# VALIDATION AND RESULTS

qualitative evaluation

**Experiments and evaluation are performed on DRIVE dataset** 



# quantitative evaluation



evaluation metrics Our results are compared with the state-of-the-art in terms of sensitivity and specificity  $Se = \frac{1}{TP + FN}$ 

Our method is statistically tied with the performance of a second expert annotator, and achieves a much higher sensitivity than all other current segmentation systems.

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